

Distributed k -Clustering with Heavy Noise (NeurIPS 2018 Poster)

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Introduction

- **Input:** Data set P from metric space (X, d) of size n . P is distributed onto m different machines as $P = P_1 \cup P_2 \cup \dots \cup P_m$.
- **Output:** A set $C \subset P$ of k centers and a set $Z \subset P$ of z outliers, that minimize some cost function $\text{cost}(P \setminus Z, C)$:
 - (k, z) -center: $\text{cost}(A, B) := \max_{p \in A} d(p, B)$
 - (k, z) -median: $\text{cost}(A, B) := \sum_{p \in A} d(p, B)$
 - (k, z) -means: $\text{cost}(A, B) := \sum_{p \in A} d^2(p, B)$
- **Communication model:** The **MapReduce** model. There exists a single coordinator S , and only communication between the coordinator and the machines are allowed.
- **Major concerns:**
 - **Clustering quality:** The solution (C, Z) should achieve $O(1)$ -approximation, i.e. $\text{cost}(P \setminus Z, C) \leq O(1) \cdot \text{OPT}$.
 - **Communication cost:** Focus on the case when data is heavily noisy, i.e., $z \gg k, m$.

Motivating Question

Can we achieve constant approximation with communication cost $o(z)$?

- **No:** Any $O(1)$ -approximation algorithm needs $\Omega(z)$ communication cost.
- **Yes:** If we allow removing slightly more than z outliers:
Def. (C, Z) is an (α, β) -approximation if $\text{cost}(P \setminus Z, C) \leq \alpha \cdot \text{OPT}$ and $|Z| \leq \beta z$

Two-Levels Clustering Framework

- 1 Each machine i construct a local summary P'_i and send to the coordinator machine S
 - 2 The coordinator S solves a single (k, z) -clustering over the aggregated summaries $\cup_{i \in [m]} P'_i$ to get final solution (C, Z) .
- **Folklore:** view each summary P'_i as local clustering centers on P_i , then if each P'_i incurs small clustering cost, S can find a good global centers by clustering $\cup_{i \in [m]} P'_i$.

Distributed (k, z) -Center

Results

	approx. ratio	comm. cost
[MKCWM15]	$(O(1), 1)$	$O(m(k+z))$
[GLZ17]	$(O(1), 2+\epsilon)$	$\tilde{O}(m(k+\epsilon^{-1}))$
Ours	$(O(1), 1+\epsilon)$	$\tilde{O}(mk\epsilon^{-1})$

Local Summary Construction

Parameter: A number $L > 0$.

- 1 **While** $\exists p \in P_i$ s.t. $|\text{ball}(p, 2L) \cup P_i| > \frac{\epsilon z}{km}$:

- Add p to P'_i and set $w'_p = |\text{ball}(p, 4L) \cup P_i|$
- Remove $\text{ball}(p, 4L)$ from P_i

- 2 **Lemma.** If $L \geq \text{OPT}$, then $\sum_{i \in [m]} |P'_i| \leq mk(1+\epsilon^{-1})$ and $\sum_{i \in [m]} \sum_{p \in P'_i} w_p \geq n - (1+\epsilon)z$.

- 3 **Remark.**

- the total size $\sum_{i \in [m]} |P'_i|$ determines the communication cost
- the total weight $\sum_{i \in [m]} \sum_{p \in P'_i} w_p$ is the number of points in P "covered" by the summary

The Whole Algorithm

- 1 The coordinator **guesses** a number L .
- 2 Each machine constructs local summary $(P'_i, \{w_p\}_{p \in P'_i})$ w.r.t. L .
- 3 Each machine sends its $|P'_i|$ and $\sum_{p \in P'_i} w_p$ to the coordinator.
 - if $\sum_{i \in [m]} |P'_i| > mk(1+\epsilon^{-1})$, the coordinator guesses a larger L ;
 - if $\sum_{i \in [m]} \sum_{p \in P'_i} w_p < n - (1+\epsilon)z$, the coordinator guesses a smaller L ;
- 4 The coordinator solves a weighted $(k, (1+\epsilon)z)$ -center problem over $\cup_{i \in [m]} P'_i$.

Theorem 1. We can find a $L \leq (1+\epsilon)\text{OPT}$ and a solution (C, Z) s.t.

- The communication cost is $mk(1+\epsilon^{-1})$.
- $\text{cost}(P \setminus Z, C) = O(1)L$ and $|Z| \leq (1+\epsilon)z$.

Distributed (k, z) -Median/Means

Results

(k, z) -median	approx. ratio	comm. cost
[GLZ17]	$(O(1), 2+\epsilon)$	$\tilde{O}(m(\epsilon^{-1}+k))$
[CAZ18]	$(O(1), 1)$	$O(k \log n + z)$
Ours	$(1+\epsilon, 1+\epsilon)$	$\tilde{O}(k\epsilon^{-3} + mk\epsilon^{-1})$

(k, z) -means

[GLZ17]	$(O(1+1/\delta), 2+\delta+\epsilon)$	$\tilde{O}(m(\delta^{-1}+k))$
[CAZ18]	$(O(1), 1)$	$O(k \log n + z)$
Ours	$(1+\epsilon, 1+\epsilon)$	$\tilde{O}(k\epsilon^{-5} + mk\epsilon^{-1})$

- The algorithm need exponential running time (in m, k, ϵ^{-1}).

Local Summary Construction

Parameter: A number $L > 0$.

- 1 Each machine i samples a **coreset** Q_i^L w.r.t. a cost function defined by threshold distance:
 $\text{cost}_L(P, C) := \sum_{p \in P} d_L(p, C)^l - zL^l$, where $d_L(p, C) := \min\{L, d(p, C)\}$, and $l = 1, 2$ for (k, z) -median/means respectively.

- 2 **Lemma.** Let (C^*, Z^*) denote the optimal solution, then $\text{cost}(P \setminus Z^*, C^*) = \sup_{L>0} \{\sum_{p \in P} d_L(p, C^*)^l - zL^l\}$

- 3 **Remark.** For each fixed L , the (k, z) -clustering problem is converted to a k -clustering problem.

The Whole Algorithm

- 1 Discretize the set of all possible L as $\mathbb{L} = \{L_{\min}, (1+\epsilon)L_{\min}, (1+\epsilon)^2 L_{\min}, \dots, L_{\max}\}$
- 2 Each machine i creates multiple local summaries, one for each $L \in \mathbb{L}$.
- 3 The coordinator solves a **min-max k -clustering problem** on the aggregated coresets: $\min_C \sup_{L \in \mathbb{L}} \text{cost}_L(P, C)$.