1. The requested MATLAB® functions are as follows.

```
function [x k] = forward(a,b,c,x0,tol)
% function [x k] = forward(a,b,c,x0,tol)
% Uses "forward" fixed-point iteration x(k+1) = -(1/a)(b + c/x(k)),
% to find a root x of the quadratic equation ax^2 + bx + c = 0. x0
% is the initial iterate, and |x(k+1)-x(k)| <= tol/2 controls the
% termination. Also returned is the total number k of iterations.
x = -(b + c/x0)/a; k = 1; % single iteration so far.
err = abs(x-x0);
while err > 0.5*tol
    x0 = x;
x = -(b + c/x0)/a; k = k+1;
err = abs(x-x0);
end
```

```
function [x k] = backward(a,b,c,x0,tol)
% function [x k] = backward(a,b,c,x0,tol)
% Uses "backward" fixed-point iteration x(k+1) = -c/(b + ax(k)),
% to find a root x of the quadratic equation ax^2 + bx + c = 0. x0
% is the initial iterate, and |x(k+1)-x(k)| <= tol/2 controls the
% termination. Also returned is the total number k of iterations.
x = -c/(b + a*x0); k = 1; % single iteration so far.
err = abs(x-x0);
while err > 0.5*tol
x0 = x;
x = -c/(b + a*x0); k = k+1;
err = abs(x-x0);
end
```

The quadratic equation $x^2 - bx - 1 = 0$ in question has roots $x_{\pm} = \frac{1}{2}(1 \pm \sqrt{5})$, or

```
x_{+} \simeq 1.618033988749895e + 00, \qquad x_{-} \simeq -6.180339887498949e - 01.
```

At the command line we verify that each of our fixed-point schemes finds one of these roots to the desired tolerance.

Clearly, forward finds x_+ and backward finds x_- . In both cases the iterations k required to achieve the 1e-10 tolerance is about 30. Note that 1.1592e-11 $< \frac{1}{2}$ tol = 5.0e-11. So, despite the termination condition being between *successive iterates*, the tolerance is achieved relative to the *actual root*. To test whether these results depend on x0, we try the following (now x0 = -10).

So the results are essentially the same. Indeed, experimentation with several choices for x0 in the range [-100, 100] always yields the same roots in about 30 or so iterations.

We now perform the following experiment. We use the returned root from forward as the x0 for backward, in both cases with tol = 1e-10. Here is the result.

So after 1 iteration, the backward iteration returns x, so let us denote this x by x_1 . Then, as is evident, $|x_0 - x_1| \simeq 4.1940e-11 \le 5.0-11$, and so the termination from backward is indeed what was specified. Moreover, we have also demonstrated above that $|x_+ - x_1| \simeq 3.0348e-11$. Note this is larger than the error $|x_+ - x_0| \simeq 1.1592e-11$ associated with x0 (the approximate root returned from forward obeyed this estimate, as seen on the first page). Now, performance of the same experiment with tol = 1e-13 for the backward iteration yields (we print out x0 just to confirm that it remains the root returned by the forward iteration).

We have converged to the x_{-} root!

The explanation for this phenomena is as follows. In fact, both x_{-} and x_{+} are fixed-points for the backward iteration. Indeed, for x_{+} one can check that

$$-\frac{c}{b+ax_{+}} = \frac{1}{-1+x_{+}} = \frac{1}{-1+\frac{1}{2}(1+\sqrt{5})} = \frac{1}{\frac{1}{2}(\sqrt{5}-1)} = \frac{2}{\sqrt{5}-1} \left(\frac{\sqrt{5}+1}{\sqrt{5}+1}\right) = \frac{1}{2}(1+\sqrt{5}) = x_{+}.$$

Here $g_{\text{backward}}(x) = 1/(-1+x)$, so the last equation is $g_{\text{backward}}(x_+) = x_+$. However,

$$g'_{\text{backward}}(x_+) = -\frac{1}{(-1+x_+)^2} = -\frac{1}{\left(\frac{1}{2}(\sqrt{5}-1)\right)^2} = -\frac{4}{(\sqrt{5}-1)^2} \simeq -2.6180.$$

Likewise, for the other root x_{-} , we find

$$x_- = g_{\mathrm{backward}}(x_-), \qquad g'_{\mathrm{backward}}(x_-) \simeq -3.8197 \mathrm{e}\text{-01}.$$

So far, we have just confirmed that the backward iteration is locally convergent for x_{-} and locally divergent for x_{+} , as expected. Moreover, from this analysis, we see that the errors associated with backward behave as

$$e_{k+1} \simeq 2.6180 e_k$$

near x_+ . This is clearly not convergent behavior. Nevertheless, in the first case above, we called backward with an x0 for which $e_0 = |x_+ - x_0| = 1.1592e-11$. Therefore, after one iteration, we expect that

$$e_1 = |x_+ - x_1| \simeq (2.6180)(1.1592e-11) \simeq 3.0348e-11.$$

This is precisely what we found above. The error has gotten worse with one iteration, but the new iterate x_1 still yields an exit from backward since $|x_1 - x_0| \le 5.0e-11$. However, when backward is called with the tighter tol = 1e-13, then the iteration can continue until the region of attraction for the fixed point x_- is reached (this fixed point is convergent for backward).

2. First we have written the following function.

```
% Returns y = sinh(x) - cos(x), first function (fun1) for hw03
% function y = hw03_fun1(x)
function y = hw03_fun1(x)
y = sinh(x) - cos(x);
```

With this MATLAB® function for $f(x) = \sinh x - \cos x$, the required tasks set down in the problem are performed by the following script.

```
% Script: hw03Problem2.m
% Solves Problem 2 for hw03. Uses hw03_fun1, external function sinh(x)-cos(x).

% First used bisection starting with bracketing interval [a,b] = [0,1].
format long e; format compact;
a = 0; b = 1; tol = 1e-8; kmax = 1000;
[r_bisection k] = bisection(@hw03_fun1,a,b,tol,kmax);
disp(['with ',num2str(k),' chops bisection found ',num2str(r_bisection,'%1.15e')])

% Next use fzero to find same root. First alter the default tolerance.
My0ptions = optimset('TolX',tol);
r_fzero = fzero(@hw03_fun1,1,My0ptions);
disp(['fzero with TolX = ',num2str(tol),' found ',num2str(r_fzero,'%1.15e')])
```

```
%
r_fzero_long = fzero(@hw03_fun1,1);
disp(['fzero with default TolX found ',num2str(r_fzero_long,'%1.15e')])
%
disp([' '])
disp(['error |r_bisection - r_fzero(1e-8tol)| ',num2str(abs(r_bisection - r_fzero),'%1.4e')])
disp(['error |r_bisection - r_fzero(Default)| ',num2str(abs(r_bisection - r_fzero_long),'%1.4e')])
```

Here is the output from the script.

```
>> hw03Problem2
with 26 chops bisection found 7.032906562089920e-01
fzero with TolX = 1e-08 found 7.032906590051011e-01
fzero with default TolX found 7.032906588639654e-01
error |r_bisection - r_fzero(1e-8tol)| 2.7961e-09
error |r_bisection - r_fzero(Default)| 2.6550e-09
```

3. To get some idea where the roots lie, we have first made the plot shown in Fig. 1. Using the

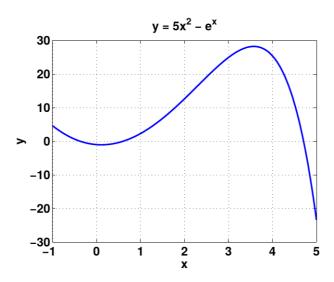


Figure 1: Plot for Problem 3.

figure, we have written the following script.

```
% Script: hw03Problem3.m
% Solves Problem 3 for hw03. Uses hw03_fun2, external function 5x^2 - e^x.

% This will not change, so fix upfront.
tol = 1e-8; kmax = 1000;

% Compute the roots using bisection.
% From plot, [-1,0] brackets leftmost root.
a1 = -1; b1 = 0; [r1_bisect k1] = bisection(@hw03_fun2,a1,b1,tol,kmax);
% From plot, [0,1] brackets middle root.
a2 = 0; b2 = 1; [r2_bisect k2] = bisection(@hw03_fun2,a2,b2,tol,kmax);
% From plot [4,5] brackets rightmost root.
a3 = 4; b3 = 5; [r3_bisect k3] = bisection(@hw03_fun2,a3,b3,tol,kmax);
```

```
clc
fprintf('Roots found with bisection algorithm\n')
fprintf('-----\n')
fprintf('with %2i chops and bracket interval [a,b]=[%2i,%2i] bisection found %+1.15e\n',k1,a1,b1,r1_bisect)
fprintf('with %2i chops and bracket interval [a,b]=[%2i,%2i] bisection found %+1.15e\n',k2,a2,b2,r2_bisect)
fprintf('with %2i chops and bracket interval [a,b]=[%2i,%2i] bisection found %+1.15e\n',k3,a3,b3,r3_bisect)
% Next use fzero to find same roots. First alter the default tolerance.
MyOptions = optimset('TolX',tol);
start1 = -1; r1_fzero = fzero(@hw03_fun2,start1,MyOptions);
start2 = 1; r2_fzero = fzero(@hw03_fun2,start2,MyOptions);
start3 = 5; r3_fzero = fzero(@hw03_fun2,start3,MyOptions);
fprintf('\n')
fprintf('Roots found with fzero algorithm\n')
fprintf('----
fprintf('fzero with TolX = %1.1e and start %+2i found
                                                                    %+1.15e\n',tol,start1,r1_fzero)
fprintf('fzero with TolX = %1.1e and start %+2i found
                                                                      %+1.15e\n',tol,start2,r2_fzero)
fprintf('fzero with TolX = %1.1e and start %+2i found
                                                                      %+1.15e\n',tol,start3,r3_fzero)
% Display the errors between roots found by both methods.
err1 = abs(r1_bisect - r1_fzero);
err2 = abs(r2_bisect - r2_fzero);
err3 = abs(r3_bisect - r3_fzero);
fprintf('\n')
fprintf('Errors between two methods\n')
fprintf('----\n')
fprintf('|r1_bisect - r1_fzero(1e-8tol)|: %1.4e\n',err1)
fprintf('|r2_bisect - r2_fzero(1e-8tol)|: %1.4e\n',err2)
fprintf('|r3_bisect - r3_fzero(1e-8tol)|: %1.4e\n',err3)
```

Here is the output from the script.

```
Roots found with bisection algorithm
```

4. The answer is g'(1) = 1 which corresponds to the arrangement shown in Fig. 2. Let us verify this result theoretically, but first argue graphically that it is so. We are told that x = 1 is a fixed point, and so the graphs y = x and y = g(x) must touch for x = 1, and there are two ways this can happen: (i) a tangent touch or (ii) a crossing touch. Fig. 2 depicts the type (i) touch for which y = x is tangent to the graph y = g(x) at x = 1, so indeed g'(1) = 1. Moreover, the figure clearly also shows that the other conditions [that is g'(-3) = 2.4 and |g'(2)| < 1] are achievable when g'(1) = 1. However, as indicated in the plots shown in Fig. 3, for (ii) the crossing touch at x = 1 always leads to $g'(2) \ge 1$, as seen in the two depicted possibilities. In Fig. 3b we have y = x tangent to y = g(x) at x = 2. Note that in all three plots g'(-3) = 2.4 (or at least g'(-3) > 1 obviously).

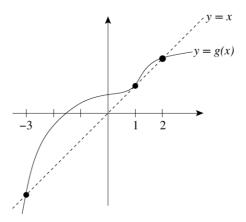


Figure 2: Sketch for Problem 4. Here |g'(2)| < 1 is possible.

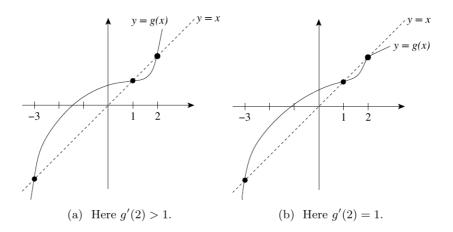


Figure 3: Sketch for Problem 4.

To obtain the result theoretically, we write

$$q(x) = w(x)(x+3)(x-1)(x-2) + x,$$

which manifestly yields fixed points at x = -3, 1, 2. Since g(x) is continuously differentiable, w(x) is at least continuous. Now

$$g'(-3) = 2.4 \implies w(-3) = 7/100 > 0.$$

Moreover, since |g'(2)| < 1 (we are told the fix-point iteration is locally convergent at x = 2), we have

$$-1 < q'(2) < 1 \implies -2 < 5w(2) < 0 \implies w(2) < 0.$$

Since w(x) is continuous, and [-3,2] is a bracketing interval, by the *Intermediate Value Theorem* there must be at least one root r on (-3,2). However, if w(r) = 0, then r is a fixed point of x = g(x); whence, since we are told that there are exactly three fixed points (namely, -3,1,2), it must be the case that r = 1. That is w(1) = 0. Clearly then, g'(1) = -4w(1) + 1 = 1, as claimed.